



## Features

- ✓ 12x optical isolated digital inputs. Support counter mode
- ✓ 12x 500 mA current sink digital outputs. Support pulse generator mode.
- ✓ 1MB battery backup SRAM disk. Supports disk and memory modes.
- ✓ CAN bus Support 2.0A and 2.0B protocol.
- ✓ Time stamp of CAN message
- ✓ Linux and Windows 2000, XP Software Development Kit (SDK).

## Specification

### General

<b>Bus interface</b>	PCI 104 PCI 2.0 Compliant
<b>SRAM disk</b>	<ul style="list-style-type: none"> <li>• Capacity: 1M Bytes</li> <li>• Battery backup</li> <li>• Operation mode: A.Memory Mode B.Disk Mode (Support in Linux only)</li> </ul>
<b>Digital Input</b>	<ul style="list-style-type: none"> <li>• 12 optical isolated channels</li> <li>• Operating mode: A.General digital input B.Counter mode</li> <li>• Programmable de-bounce time (0 ms to 255ms, 1 ms resolution).</li> <li>• Change of State interrupt</li> <li>• Response time: 20 uS + de-bounce time</li> <li>• Trigger: rising trigger or falling trigger</li> <li>• Signal Type: A.Open/Ground switch input B.Digital Logici. Logic High: 3V to 28V Logic Low : 0V to 1.5V8.</li> <li>• Maximum input frequency 10KHz.</li> </ul>
<b>Counter</b>	<ul style="list-style-type: none"> <li>• All digital input support counter mode</li> <li>• 12 x independent 16-bit counters</li> </ul>
<b>Digital Output</b>	<ul style="list-style-type: none"> <li>• 12 channels</li> <li>• Output Type: Open drain MOSFET driver</li> <li>• Output voltage range: 5V to 30V</li> <li>• Sink Current: maximum 500mA each channel</li> </ul>
<b>Pulse Generator</b>	<ul style="list-style-type: none"> <li>• All digital outputs support pulse generator mode</li> <li>• 12 x End of pulses interrupt capable counters</li> <li>• Programmable cycle time, duty cycle and number of cycles.</li> <li>• Maximum 65535 cycles</li> <li>• RUN &amp; STOP command</li> <li>• Programmable time unit: 1 ms, 100ms and 1 second</li> </ul>

### General

<b>Timer</b>	<ul style="list-style-type: none"> <li>• 12 x independent 16-bit timers</li> <li>• Support Time Out Interrupt</li> <li>• Programmable time unit: 1 ms and 100ms</li> </ul>
<b>CAN bus</b>	<ul style="list-style-type: none"> <li>• 1 x CAN bus</li> <li>• 2KV isolation</li> <li>• Support both CAN 2.0A and 2.0B protocol</li> <li>• Programmable baud rate: from 5K bps Maximum 1M bps or user-defined baud rate</li> <li>• Time stamp of CAN message</li> <li>• API library for user development</li> <li>• CAN bus device status query</li> <li>• Device driver for Windows 2000/XP/XPe and Linux</li> </ul>
<b>Maximum card</b>	Maximum 2 cards can be stacked up in one system
<b>Software</b>	<ul style="list-style-type: none"> <li>• Windows XP, XPe and Linux device driver and API</li> <li>• Windows XP, XPe and Linux demo program</li> <li>• User interface for DIO, SRAM and CAN bus in Linux and Windows XP embedded</li> </ul>
<b>Mechanical</b>	
<b>Dimension</b>	90.17 x 95.89mm (3.55"x3.775")
<b>Operating Temp.</b>	0°C to 60°C (32~140°F) without air flow
<b>Storage Temp.</b>	-20~80°C (-4~176°F)
<b>Relative Humidity</b>	0 to 90% @ 40°C, non-condensing